Product (Re)forms Part 1

Kristy Gardner Computer Science Department Amherst College Rhonda Righter IEOR Department

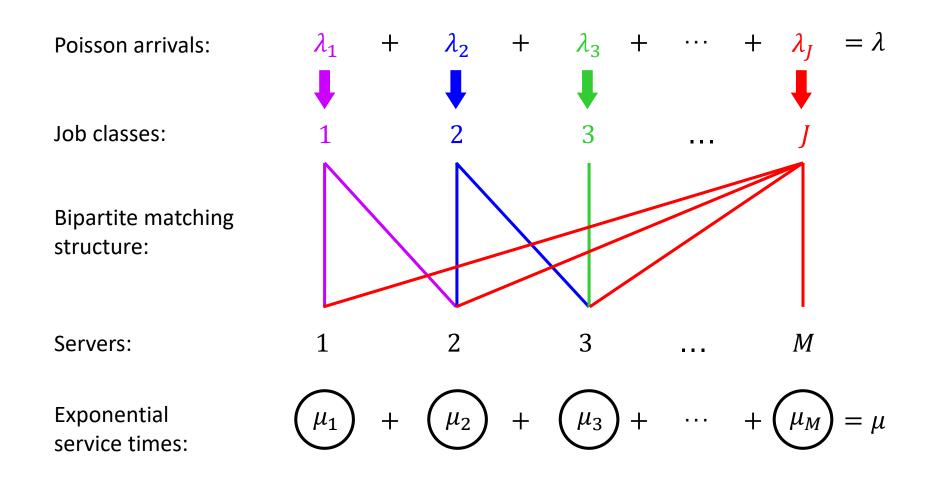
UC Berkeley

INFORMS APS, July 4, 2019

Based on work by...

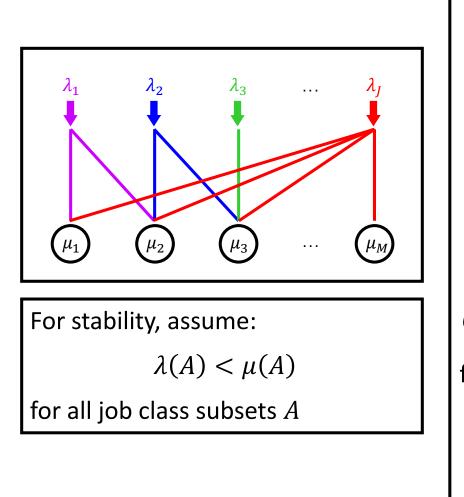
Adan, Ahn, Akgun, Anton, Atar, Ayesta, Bodas, Bonald, Busic, Caldentey, Comte, Doroudi, Dorsman, Gardner, Gel, Gupta, Harchol-Balter, Hellemans, Hopp, Hurkens, Hyytiä, Jonckheere, Kaplan, Kesslassy, Kleiner, Krzesinski, Mairesse, Mathieu, Mendelson, Moyal, Perry, Righter, Scheller-Wolf, van Houdt, Van Oyen, Velednitsky, Verloop, Visschers, Weiss, Wolff, Zbarsky...

System Structure



Curstan	Detailed states		Partial aggregation			Related systems	ſ
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	Z

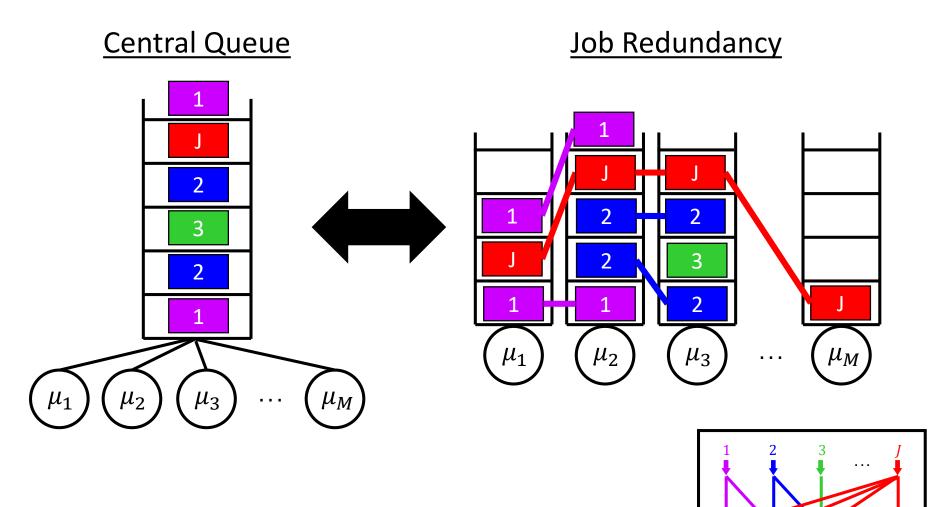
System Structure



Notation $S_i = \{k \mid \text{server } k \text{ can serve class } i\}$ for subset of job classes A: $S(A) = \bigcup_{i=1}^{n} S_i$ $\lambda(A) = \sum_{i \in A} \lambda_i \qquad \mu(A) = \sum_{k \in S(A)} \mu_k$ $\lambda = \lambda(\{1, \dots, J\}) \quad \mu = \mu(\{1, \dots, M\})$ $C_k = \{i \mid \text{server } k \text{ can serve class } i\}$ for subset of servers B: $C(B) = \bigcup C_k$ $\lambda(B) = \sum_{i \in C(B)} \lambda_i \qquad \mu(B) = \sum_{k \in B} \mu_k$

System	Detailed states		Partial aggregation			Polated systems	C
	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	5

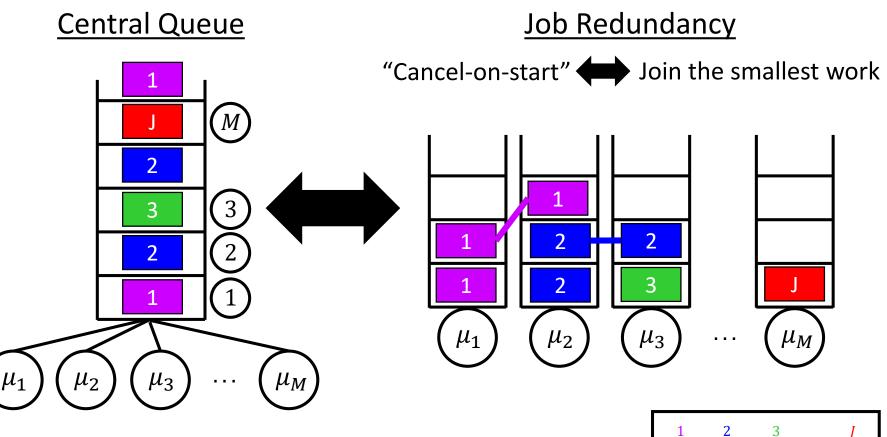
Two Equivalent Views



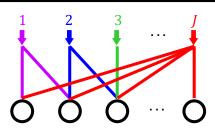
Suctor	Detailed states		Partial aggregation			Polatod systems	Л
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	4

The Noncollaborative Model

A job can be served by only one server



If multiple compatible idle servers upon arrival: Assign Longest Idle Server (ALIS) [Adan, Weiss]



Sustan	Detailed states		Partial aggregation			Polatod systems	E
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	С

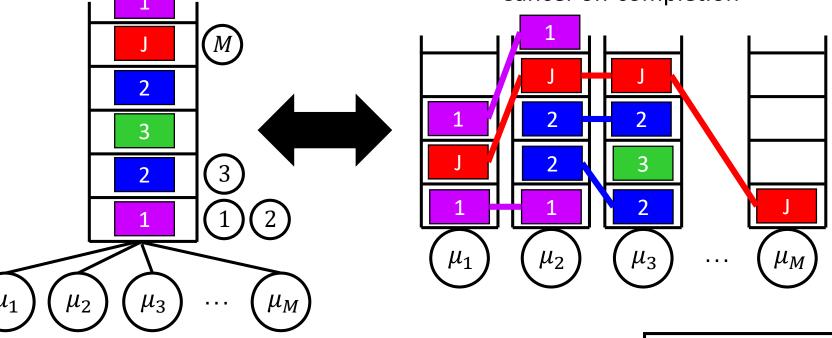
The Collaborative Model

Multiple servers can work on the same job at once, with additive service rate

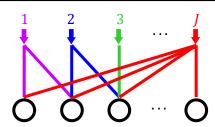
Central Queue

Job Redundancy

"Cancel-on-completion"



If multiple compatible idle servers upon arrival: job enters service on all of them



Custom	Detailed states		Partial aggregation			Related systems	6
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	D

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

Relating the models

• Partial aggregation

Collaborative model Noncollaborative model

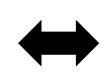
- Special case: fully flexible class
- Special case: nested systems
- Related product-form systems

Sustan	Detailed states		Partial aggregation			Polatod systems	7
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	/

Reversibility Review

<u>Def</u>: A stochastic process X(t) is <u>reversible</u> if $(X(t_0), ..., X(t_n))$ has the same distribution as $(X(t_n), ..., X(t_0))$ for all $t_0, ..., t_n$

Reversible



Detailed balance eqns

 $\pi_i v_{ij} = \pi_j v_{ji}$ for all states *i*, *j* v_{ij} : rate of going from state *i* to state *j*

<u>Def</u>: A queue is <u>quasi-reversible</u> if its state at time *t* is independent of:

- Arrival times after time *t*
- Departure times before time t

Partial balance (for our model)

Quasireversible



rate into state i

due to arrival

rate out of state i =

due to class-*c* arrival

due to departure

rate out of state *i*

= rate into state *i* due to class-*c* departure

Sustan	Detailed states		Partial aggregation			Polatod systems	0
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	Õ

Reversibility Review

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Reversible



Detailed balance eqns

 $\pi_i v_{ij} = \pi_j v_{ji}$ for all states *i*, *j* v_{ij} : rate of going from state i to state j

Def: A queue is <u>quasi-reversible</u> if its state at time *t* is independent of:

- Arrival times after time *t*
- Departure times before time t

Quasireversible



Burke's Theorem: Departure process is a Poisson process



Networks of queues have product-form stationary distribution

Custons	Detailed states		Partial aggregation			Polatod systems	0
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	Ō

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

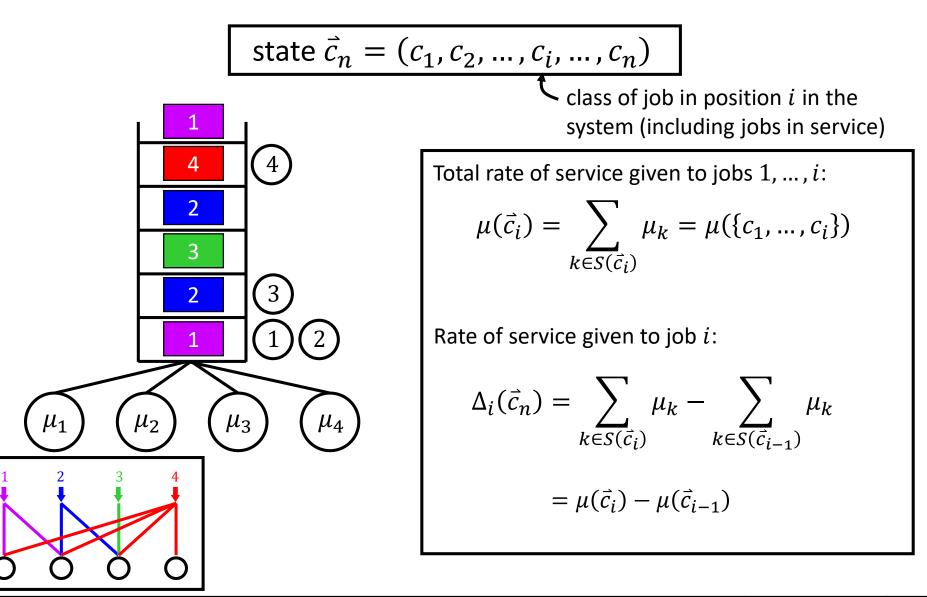
Relating the models

• Partial aggregation

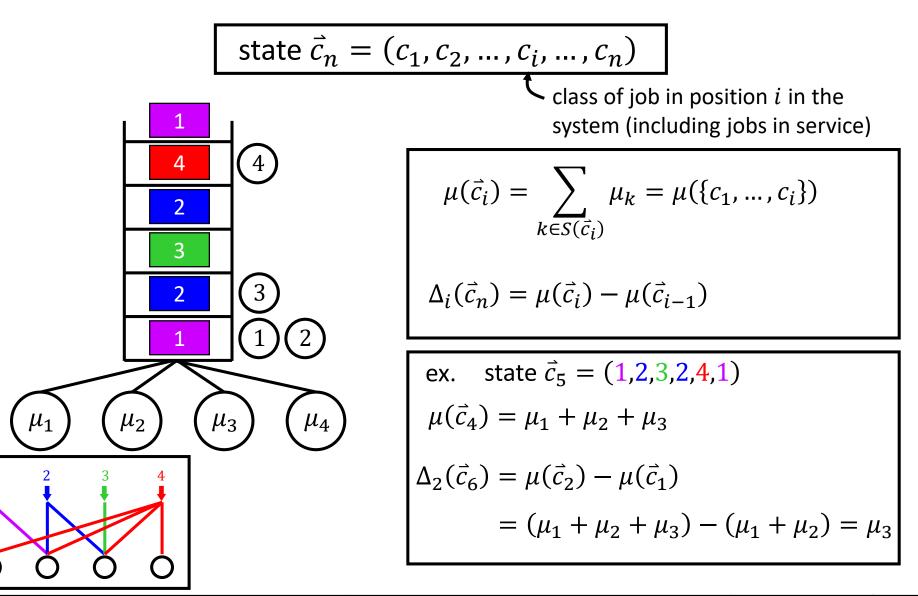
Collaborative model Noncolla

- Noncollaborative model
- Special case: fully flexible class
- Special case: nested systems
- Related product-form systems

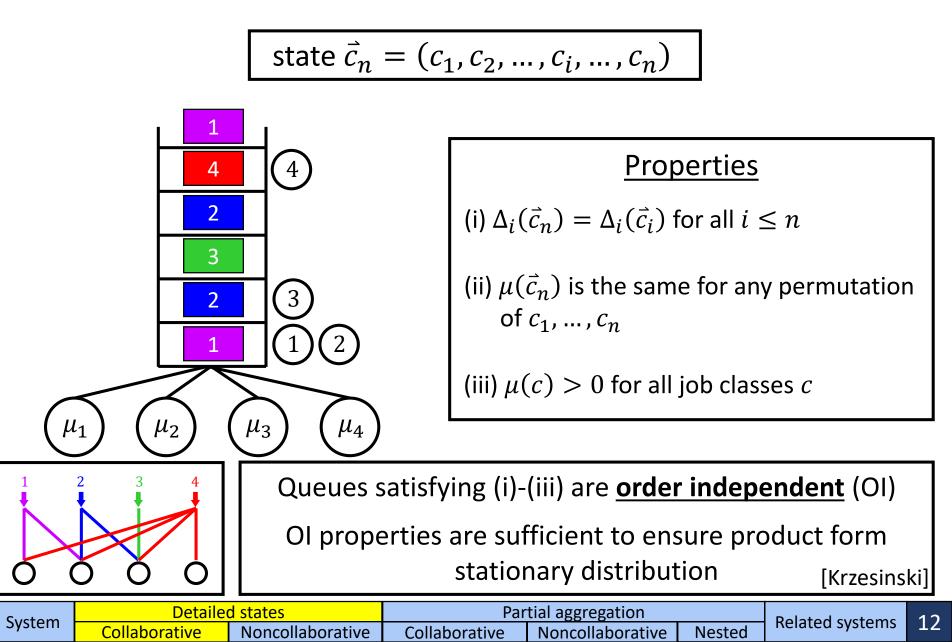
Sustan	Detailed states		Partial aggregation			Polatod systems	C
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	9



Suctor	Detailed states		Partial aggregation			Polatod systems	10
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	10



Sustam	Detailed states		Partial aggregation			Polatod cystoms	11
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	TT



Order Independence

Queues satisfying (i)-(iii) are order independent (OI)

OI properties are sufficient to ensure product form stationary distribution

Much more general than collaborative model

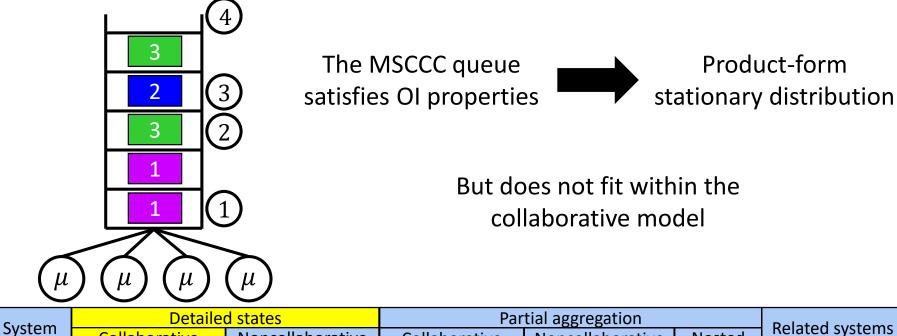
ex. Multi-Server Station with Concurrent Classes of Customers (MSCCC) queue

• All job classes are compatible with all servers

Noncollaborative

Collaborative

• At most one job per class can be in service at a time



Collaborative

Noncollaborative

Nested

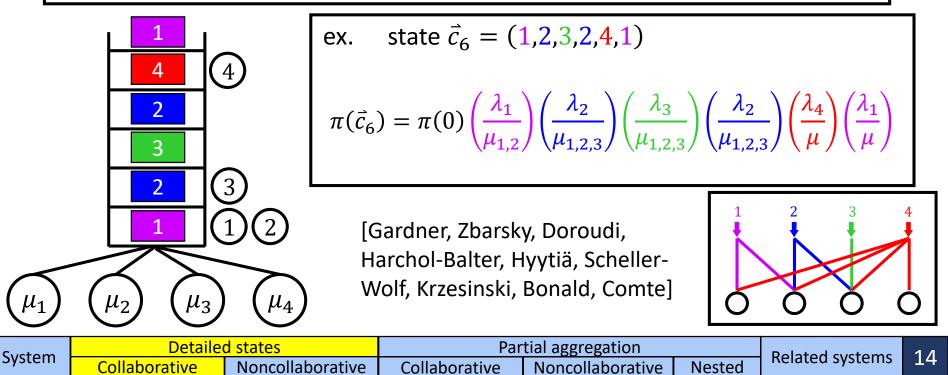
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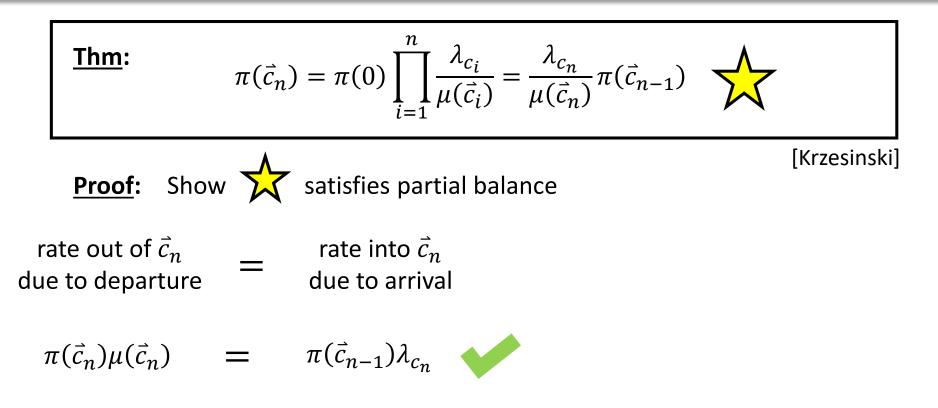
<u>Thm</u>: Given OI properties, the system is quasi-reversible and the stationary distribution is:

$$\pi(\vec{c}_n) = \pi(0) \prod_{i=1}^n \frac{\lambda_{c_i}}{\mu(\vec{c}_i)} = \frac{\lambda_{c_n}}{\mu(\vec{c}_n)} \pi(\vec{c}_{n-1}) \quad \checkmark$$

provided $G = \sum_{\vec{c}_n} \prod_{i=1}^n \frac{\lambda_{c_i}}{\mu(\vec{c}_i)} < \infty$. Then $\pi(0) = \frac{1}{G}$ is the probability

the system is empty.





Sustam	Detailed states		Partial aggregation			Polated systems	15
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	15

Base case (n = 0): $\pi(0)\lambda_c = \pi(c)\Delta_1(c) = \pi(c)\mu_c$

Sustam	Detailed states		Partial aggregation			Polatod systems	16
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	16

System	Detailed states		Partial aggregation			Polatod systems	17
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	Т/

Suctor	Detailed states		Partial aggregation			Polatod systems	17
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	1/

Suctor	Detailed states		Partial aggregation			Polatod systems	17
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	1/

$$\begin{array}{c|c} \hline \text{Thm:} & \pi(\vec{c}_n) = \pi(0) \prod_{i=1}^n \frac{\lambda_{c_i}}{\mu(\vec{c}_i)} = \frac{\lambda_{c_n}}{\mu(\vec{c}_n)} \pi(\vec{c}_{n-1}) & \swarrow & [\text{Krzesinski}] \\ \hline \text{Proof:} & \text{Show} & \swarrow & \text{satisfies partial balance} \\ \hline \text{Inductive hypothesis:} & \pi(\vec{c}_{n-1})\lambda_c = \sum_{j=1}^{n-1} \pi(c_1, \dots, c_j, c, c_{j+1}, \dots, c_{n-1})\Delta_{j+1}(\vec{c}_j, c) \\ \pi(\vec{c}_n)\lambda_c & \stackrel{?}{=} & \sum_{j=1}^{n-1} \pi(c_1, \dots, c_j, c, c_{j+1}, \dots, c_n)\Delta_{j+1}(\vec{c}_j, c) + \pi(\vec{c}_n, c)\Delta_{j+1}(\vec{c}_n, c) \\ & = & \frac{\lambda_{c_n}}{\mu(\vec{c}_n, c)} \sum_{j=1}^{n-1} \pi(c_1, \dots, c_j, c, c_{j+1}, \dots, c_{n-1})\Delta_{j+1}(\vec{c}_j, c) + \frac{\lambda_c}{\mu(\vec{c}_n, c)} \pi(\vec{c}_n)\Delta_{j+1}(\vec{c}_n, c) & (\bigstar) \\ & = & \lambda_c \pi(\vec{c}_n) & \checkmark & (\text{just a little algebra}) \end{array}$$

(just a little algebra)

System	Detailed states		Partial aggregation			Polatod systems	17
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	1/

Computations for Collaborative Model

<u>Thm</u>: $\pi(0)$ can be computed recursively:

$$\pi(0) = \frac{\mu - \lambda}{\sum_{s \in M} \frac{\mu_s}{\pi_{-s}(0)}}$$

where -s denotes a system in which server s and all job classes compatible with server s are removed

<u>Thm</u>: Let $E[N^{(i)}]$ and E[N] denote the number of class i jobs and the total number of jobs in the system. $E[N^{(i)}]$ and E[N] can be computed recursively: $E[N^{(i)}] = \frac{\lambda_i + \sum_{s \in M \setminus C_i} \mu_s \pi^{(s)}(0) E\left[N_{-s}^{(i)}\right]}{\mu - \lambda}$ $E[N] = \frac{\lambda + \sum_{s \in M} \mu_s \pi^{(s)}(0) N_{-s}}{\mu - \lambda}$

[Bonald, Comte, Mathieu]

Suctor	Detailed states		Partial aggregation			Polated systems	10
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	18

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

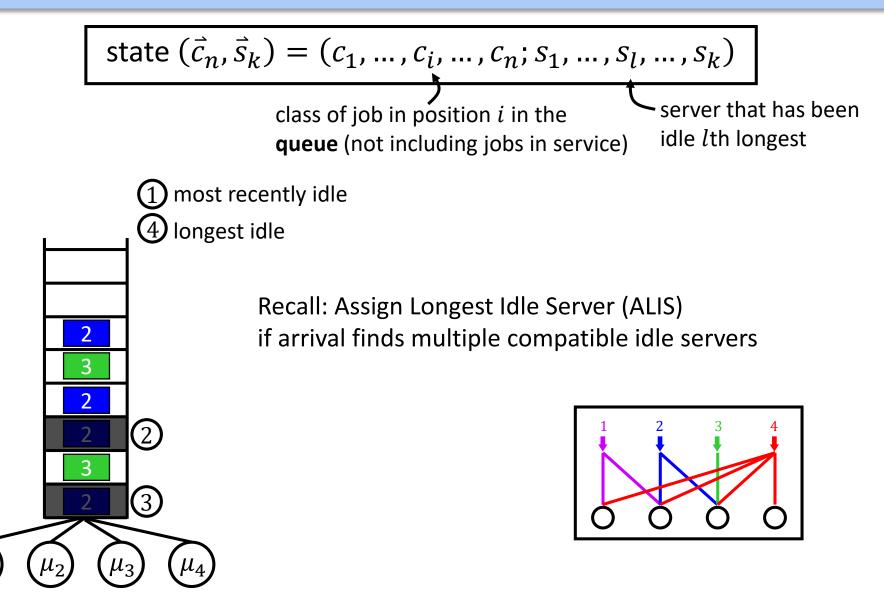
Relating the models

• Partial aggregation

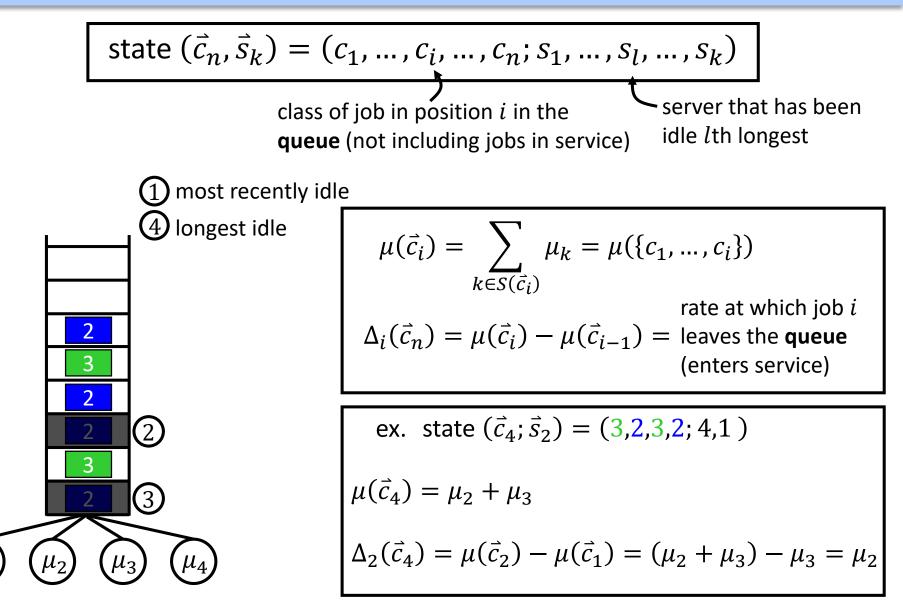
Collaborative model Noncollaborative model

- Special case: fully flexible class
- Special case: nested systems
- Related product-form systems

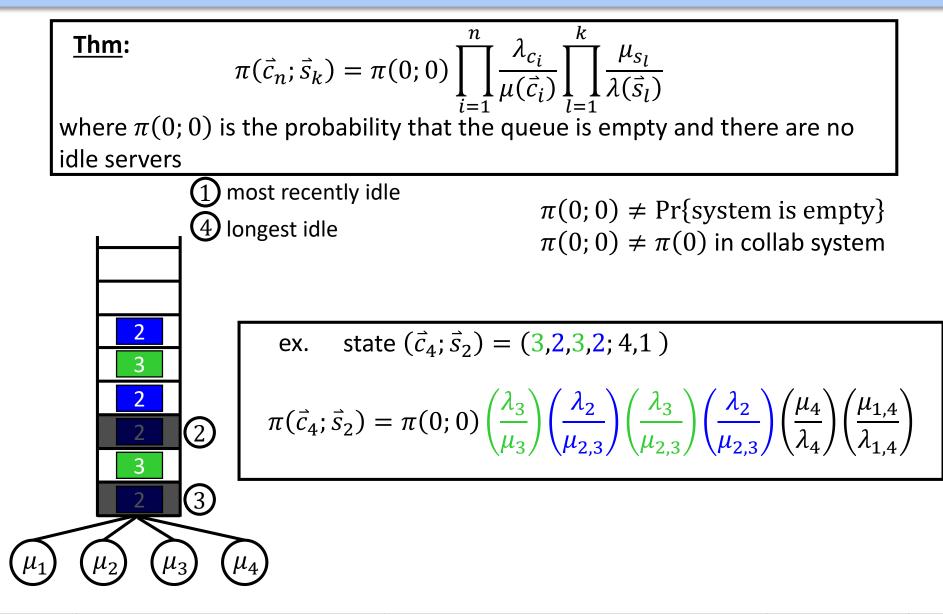
Custom	Detailed states		Partial aggregation			Polatod systems	19
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	19



Sustam	Detailed states		Partial aggregation			Related systems	20
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	20



Sustam	Detailed states		Partial aggregation			Polated systems	21
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	



Sustam	Detailed states		Partial aggregation			Related systems	าา
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	22

<u>Thm</u>:

$$\pi(\vec{c}_n; \vec{s}_k) = \pi(0; 0) \prod_{i=1}^n \frac{\lambda_{c_i}}{\mu(\vec{c}_i)} \prod_{l=1}^k \frac{\mu_{s_l}}{\lambda(\vec{s}_l)}$$

where $\pi(0; 0)$ is the probability that the queue is empty and there are no idle servers

Proof: Partial balance for job *c_i*: Similar to collaborative case

Partial balance for server *s*_{*l*}:

Let $\Delta_l^{\lambda}(\vec{s}_k) = \lambda(\vec{s}_l) - \lambda(\vec{s}_{l-1})$ denote the rate at which the *l*th idle server will become busy

Observation: idle servers satisfy OI properties:

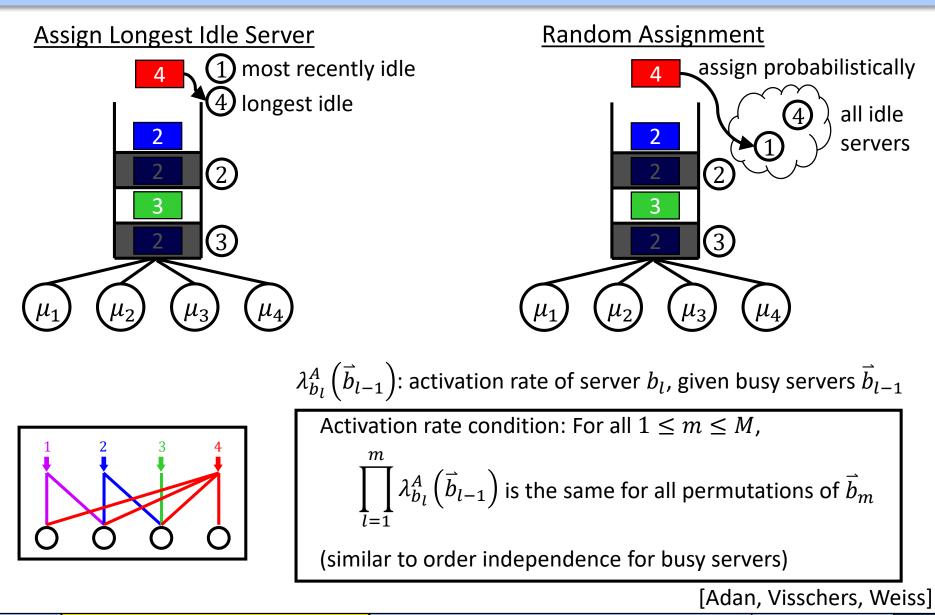
(i)
$$\Delta_l^{\lambda}(\vec{s}_k) = \Delta_l^{\lambda}(\vec{s}_l)$$
 for all $l \le k$

(ii) $\lambda(\vec{s}_l)$ is the same for any permutation of s_1, \dots, s_l

(iii) $\lambda(s) > 0$ for all servers s

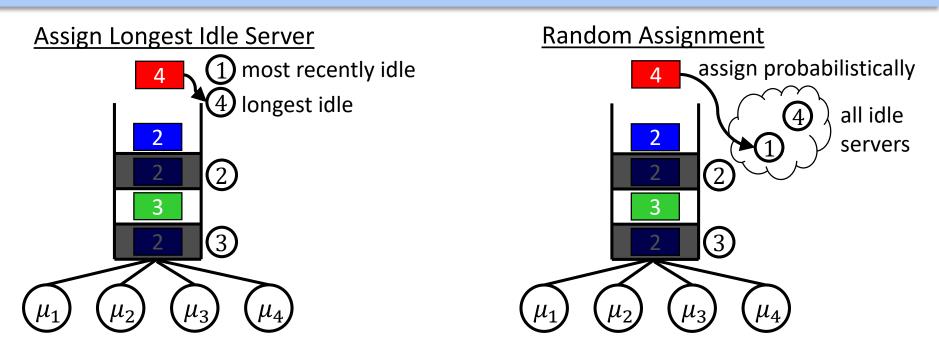
Sustan	Detailed states		Partial aggregation			Polatod systems	23
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	23

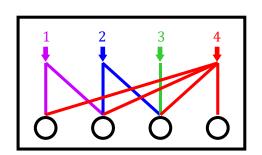
Noncollaborative with Random Assignment



Suctor	Detailed states		Partial aggregation			Polatod systems	24
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	24

Noncollaborative with Random Assignment





Thm: Given the activation rate condition:

$$\pi^{RAND}\left(\vec{c}_{n};\vec{b}_{m}\right) = \pi^{RAND}(0;0)\prod_{i=1}^{n}\frac{\lambda_{c_{i}}}{\mu(\vec{c}_{i})}\prod_{l=1}^{m}\frac{\lambda_{b_{l}}^{A}\left(\vec{b}_{l-1}\right)}{\mu\left(\vec{b}_{l}\right)}$$

[Adan, Visschers, Weiss]

System	Detaile	d states	Par	artial aggregation		Polatod systems	25
	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	25

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

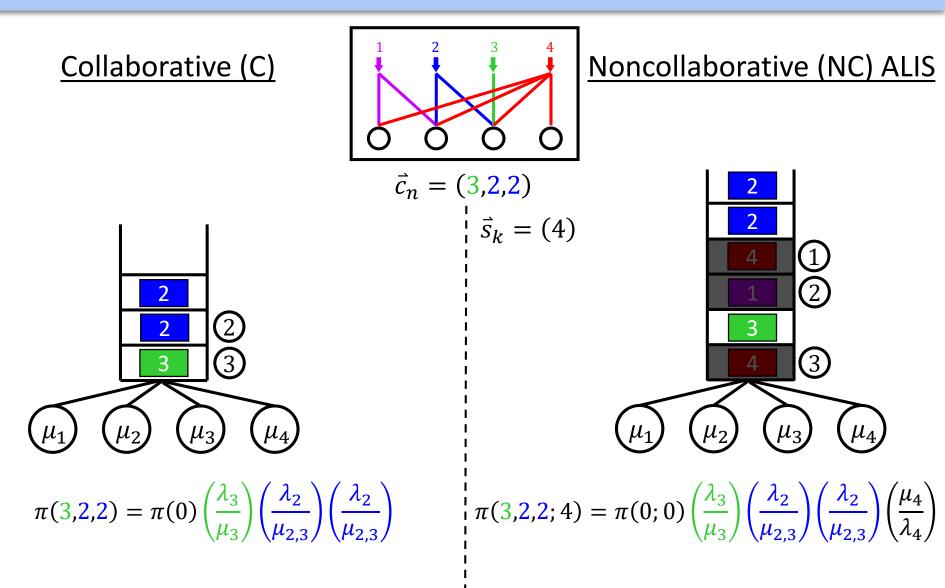
Relating the models

• Partial aggregation

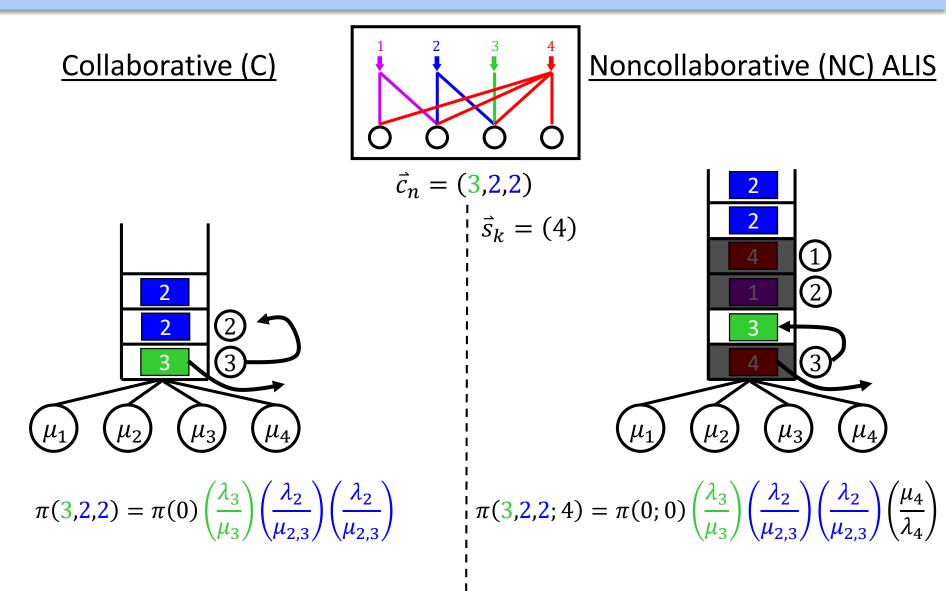
Collaborative model Noncollaborative model

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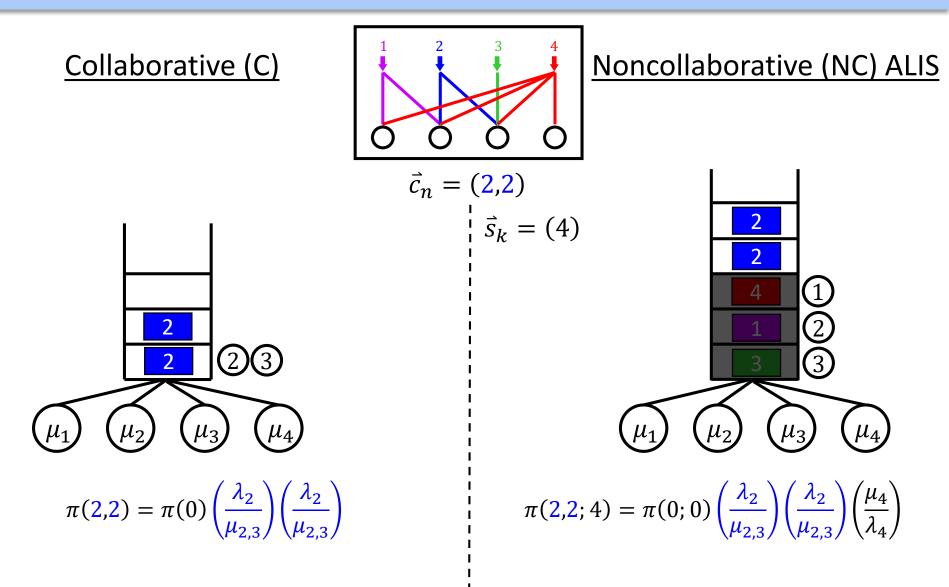
Custom	Detaile	d states	Par	tial aggregation		Related systems	
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	26



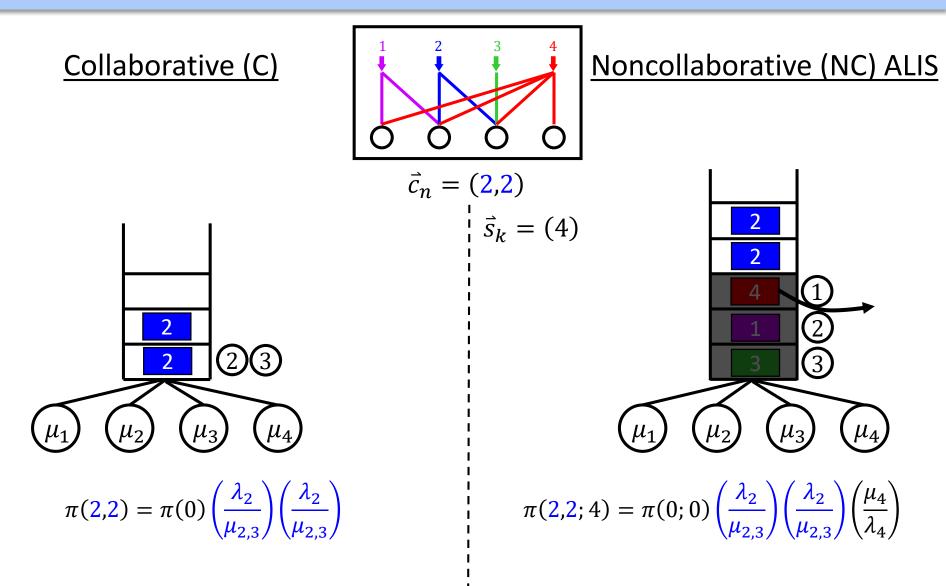
System	Detaile	d states	Par	tial aggregation		Polated systems	27
	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	27



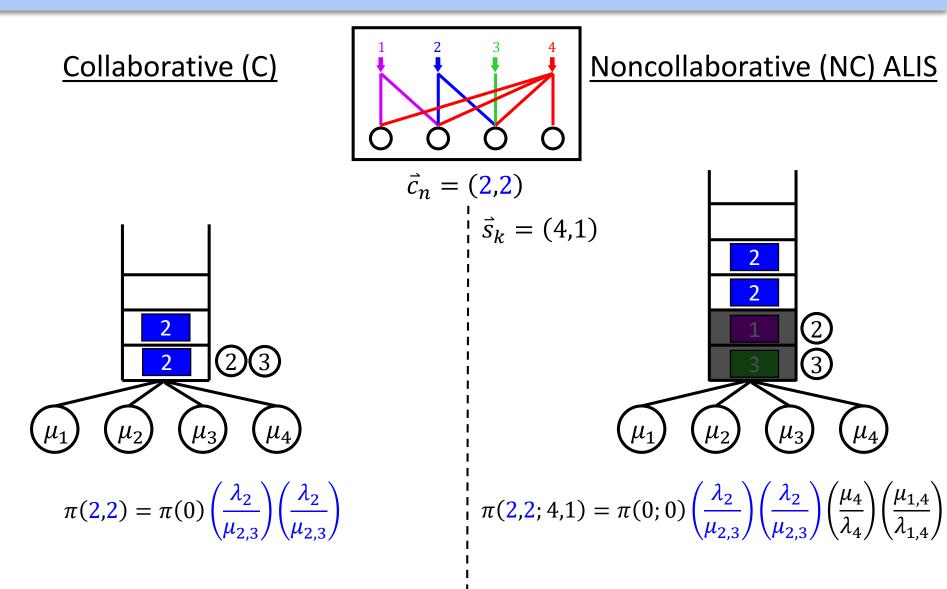
Custom	Detaile	d states	Par	rtial aggregation		Related systems	27
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	27



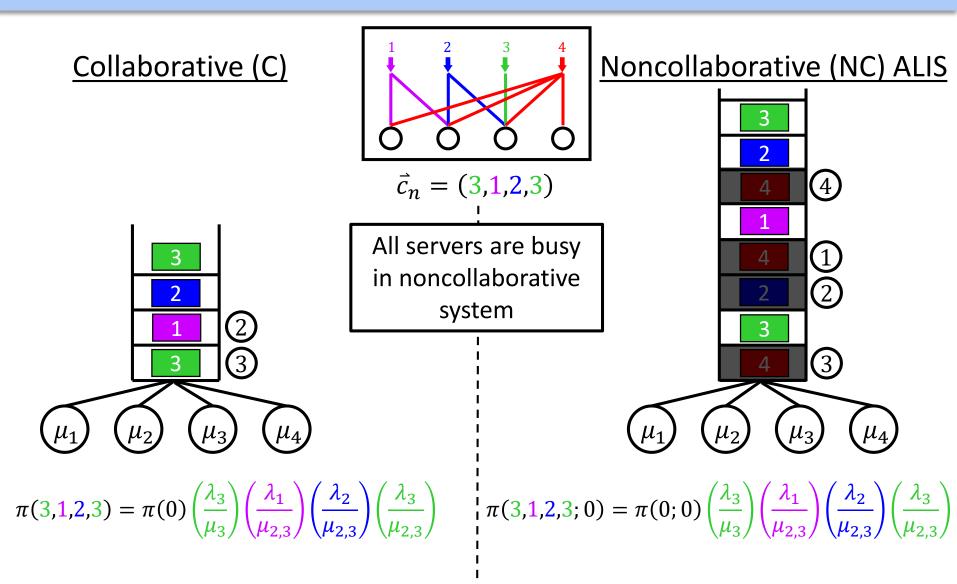
Curations	Detailed states		Partial aggregation			Delated systems	27
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	Ζ/



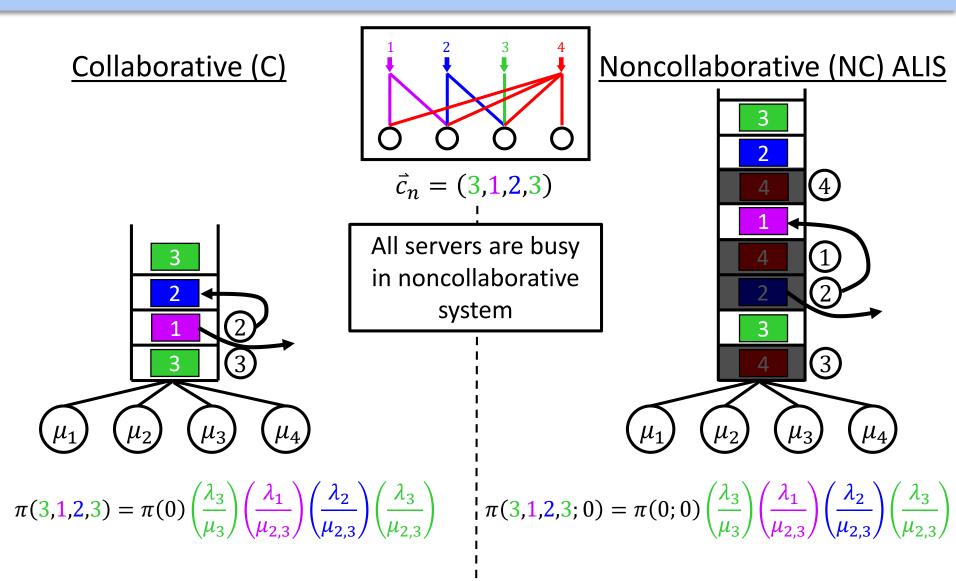
Curations	Detaile	Detailed states		Partial aggregation			27
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	Ζ/



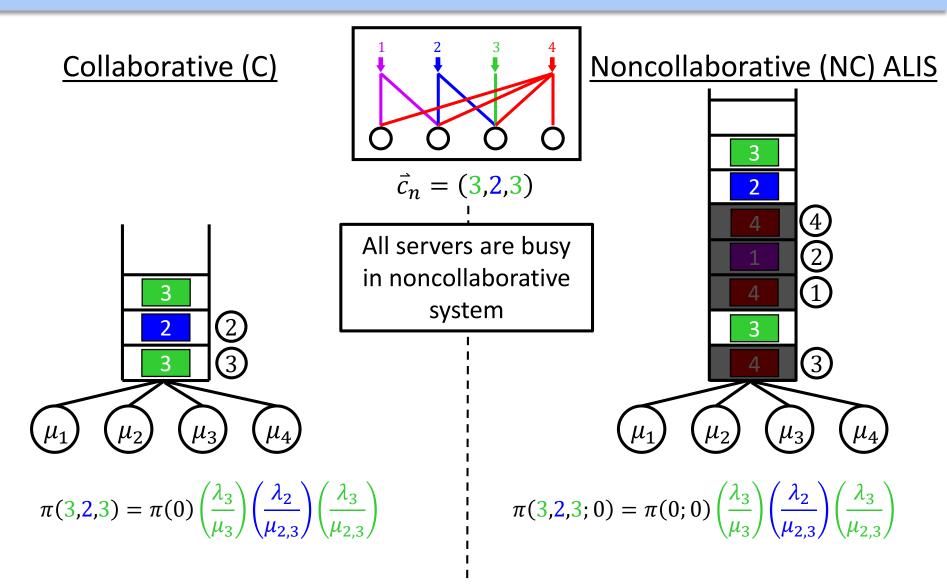
Sustam	Detailed states		Partial aggregation			Polatod systems	27
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	Ζ/



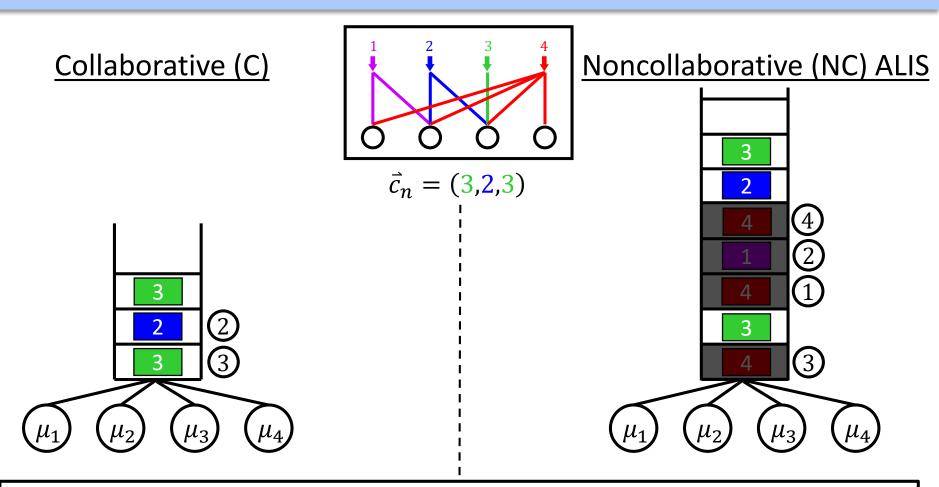
Custom	Detailed states		Partial aggregation			Polatod systems	28
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	20



Sustan	Detailed states		Partial aggregation			Related systems	าด
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	20



Suctor	Detailed states		Partial aggregation			Polatod systems	28
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	20



Conditioned on all servers being busy in NC, the noncollaborative **queue**

has the same stationary distribution as the collaborative system

			1				
System	Detailed states		Partial aggregation			Polatod systems	29
	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	29

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

Relating the models

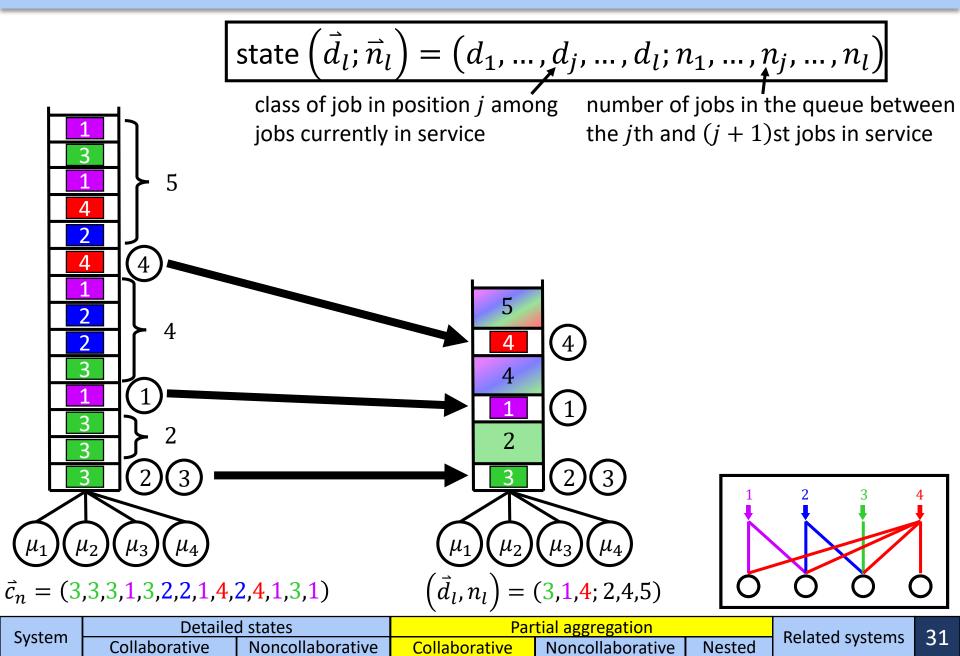
Partial aggregation

Collaborative model

Noncollaborative model

- Special case: fully flexible class
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Sustam	Detailed states		Partial aggregation			Polatod systems	20
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	50

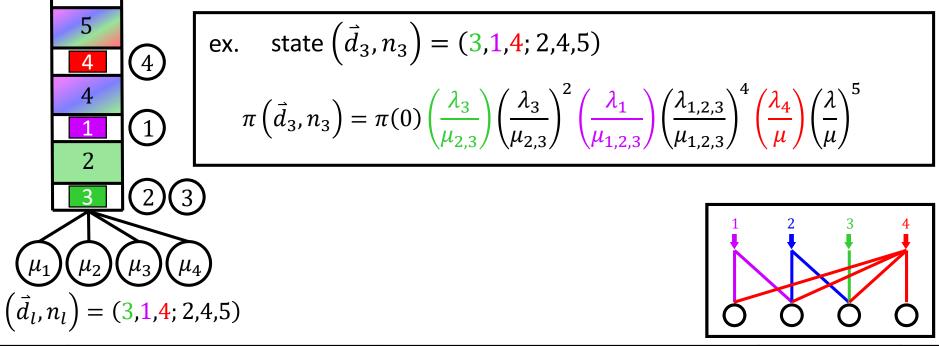


Thm:

$$\pi\left(\vec{d}_{l},\vec{n}_{l}\right) = \pi(0) \prod_{j=1}^{l} \frac{\lambda_{d_{j}}}{\mu\left(\vec{d}_{j}\right)} \left(\frac{\lambda\left(R\left(\vec{d}_{j}\right)\right)}{\mu\left(\vec{d}_{j}\right)}\right)^{n}$$
where $\pi(0)$ is the probability that the system is empty

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$$R\left(\vec{d}_{j}\right) = \left\{i \left| \text{class } i \text{ } \mathbf{R} \text{equires a server in } S\left(\vec{d}_{j}\right)\right\}$$

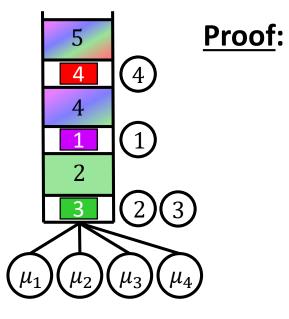


Custom	Detailed states		Partial aggregation			Polatod systems	\sim
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	52

Thm:

$$\pi\left(\vec{d}_{l},\vec{n}_{l}\right) = \pi(0) \prod_{j=1}^{l} \frac{\lambda_{d_{j}}}{\mu\left(\vec{d}_{j}\right)} \left(\frac{\lambda\left(R\left(\vec{d}_{j}\right)\right)}{\mu\left(\vec{d}_{j}\right)}\right)^{n_{j}}$$
where $\pi(0)$ is the probability that the system is empty

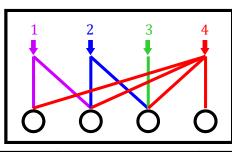
$$R\left(\vec{d}_{j}\right) = \left\{i \middle| \text{class } i \text{ } \mathbf{R} \text{equires a server in } S\left(\vec{d}_{j}\right)\right\}$$



Approach 1: Partially aggregated states satisfy partial balance

Approach 2: Sum up detailed states:

$$\pi\left(\vec{d}_{l}, \vec{n}_{l}\right) = \sum_{\substack{\vec{c}_{n} \text{ consistent}\\ \text{with } (\vec{d}_{l}, \vec{n}_{l})}} \pi(\vec{c}_{n})$$



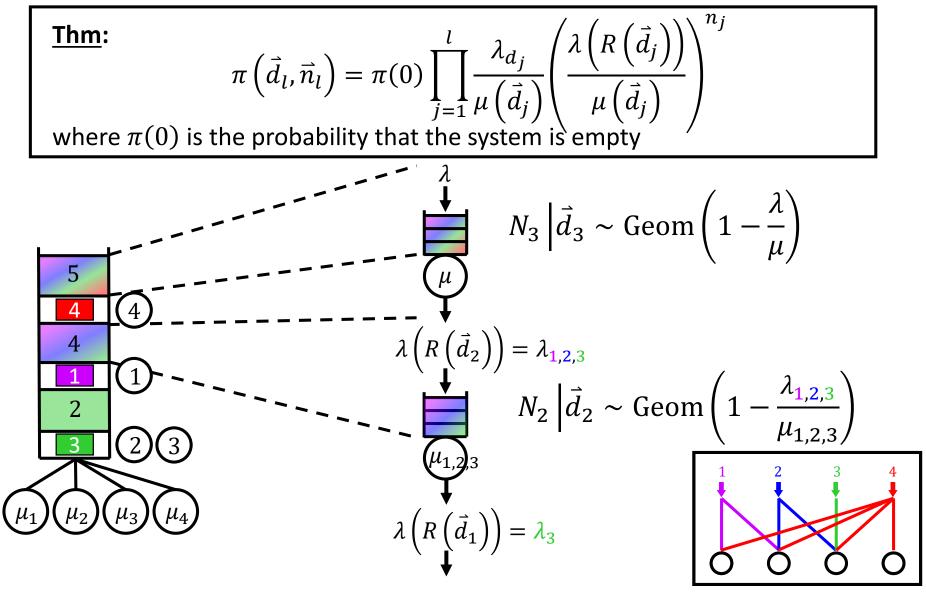
Sustam	Detailed states		Partial aggregation			Polatod systems	33
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	33

Thm:

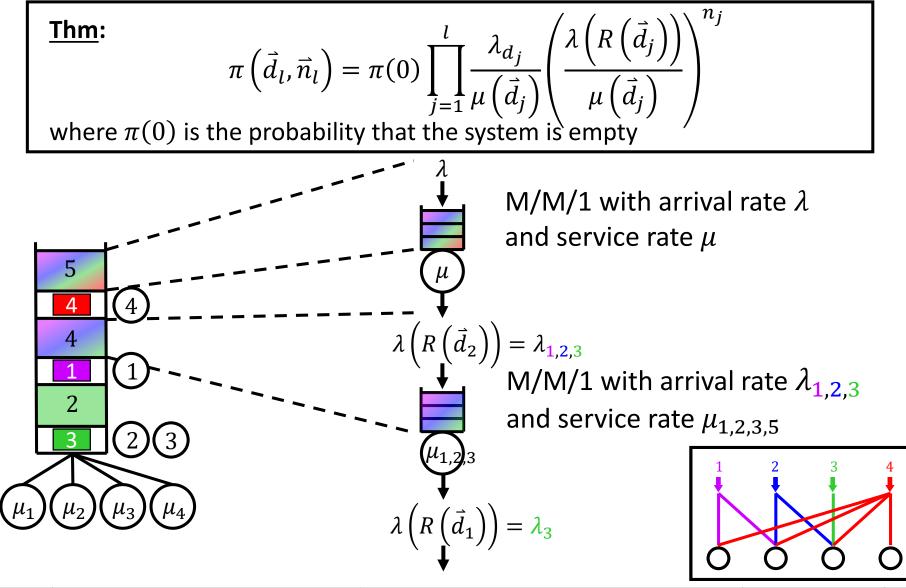
$$\pi\left(\vec{d}_{l},\vec{n}_{l}\right) = \pi(0)\prod_{j=1}^{l}\frac{\lambda_{d_{j}}}{\mu\left(\vec{d}_{j}\right)}\left(\frac{\lambda\left(R\left(\vec{d}_{j}\right)\right)}{\mu\left(\vec{d}_{j}\right)}\right)^{n_{j}}$$
where $\pi(0)$ is the probability that the system is empty

 $N_{j} = \text{\# jobs between } j \text{th and } (j + 1) \text{st jobs in service}$ $N_{j} = \text{\# jobs between } j \text{th and } (j + 1) \text{st jobs in service}$ $N_{j} | \vec{d}_{l} =_{st} N_{j} | \vec{d}_{j} \sim \text{Geom} \left(1 - \frac{\lambda \left(R\left(\vec{d}_{j}\right) \right)}{\mu \left(\vec{d}_{j}\right)} \right)$ $\frac{1}{2}$ 2 3 $\mu_{1} + \mu_{2} + \mu_{3} + \mu_{4}$ $\frac{1}{2} + \frac{1}{2} + \frac{1}{2}$

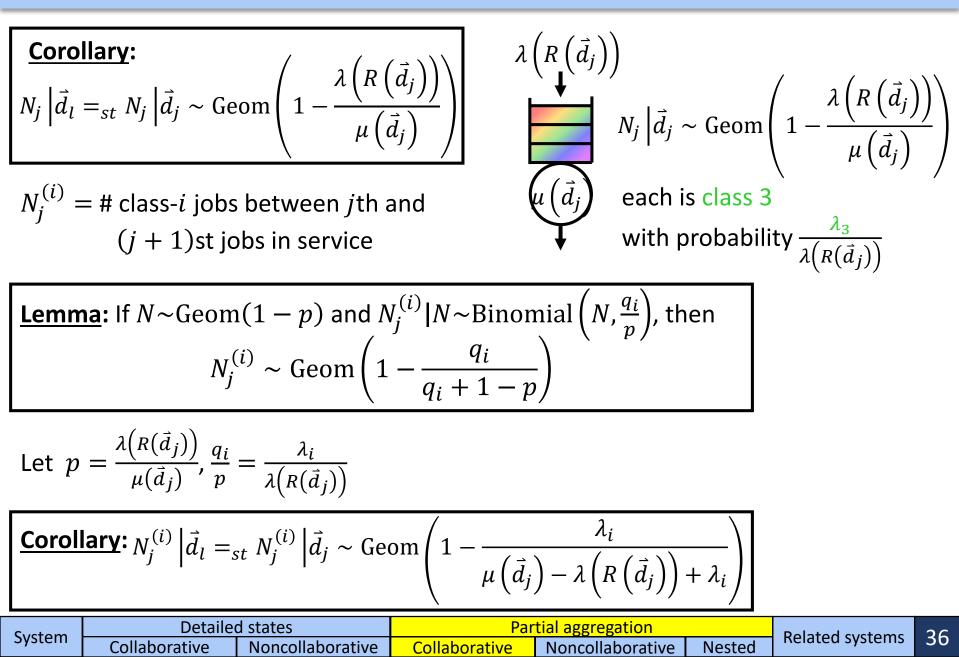
Sustam	Detailed states		Partial aggregation			Polatod systems	24
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	34



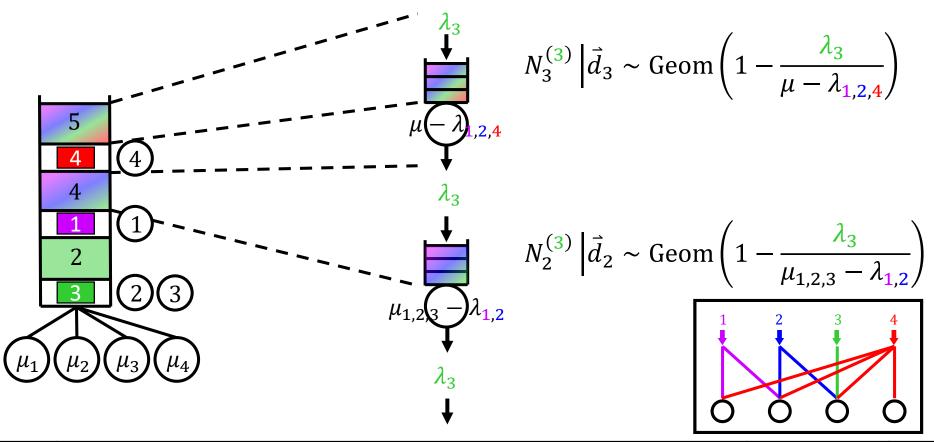
Sustam	Detailed states		Par	Related systems	Э Е		
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	35



Sustam	Detailed states		Par	Polatod systems	Э Е		
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	55

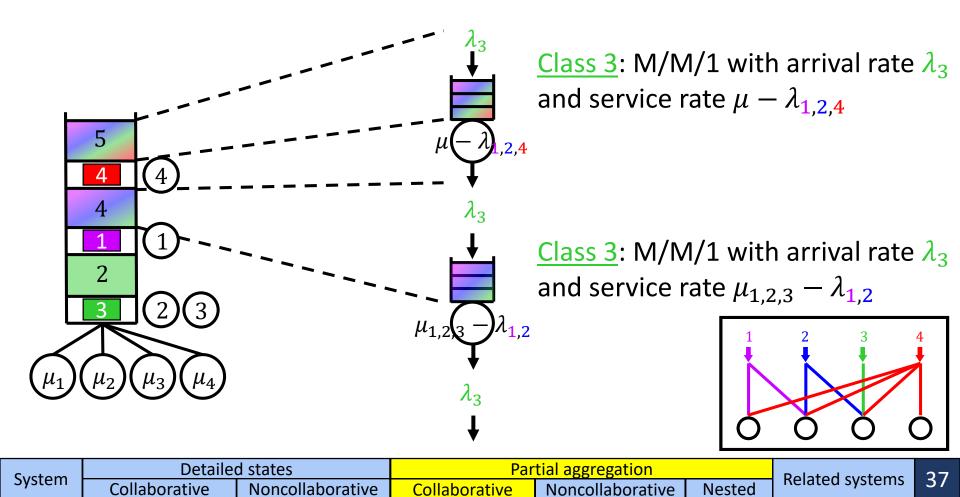


$$\underline{\text{Corollary:}} N_j^{(i)} \left| \vec{d}_l =_{st} N_j^{(i)} \left| \vec{d}_j \sim \text{Geom} \left(1 - \frac{\lambda_i}{\mu\left(\vec{d}_j\right) - \lambda\left(R\left(\vec{d}_j\right)\right) + \lambda_i} \right) \right|$$

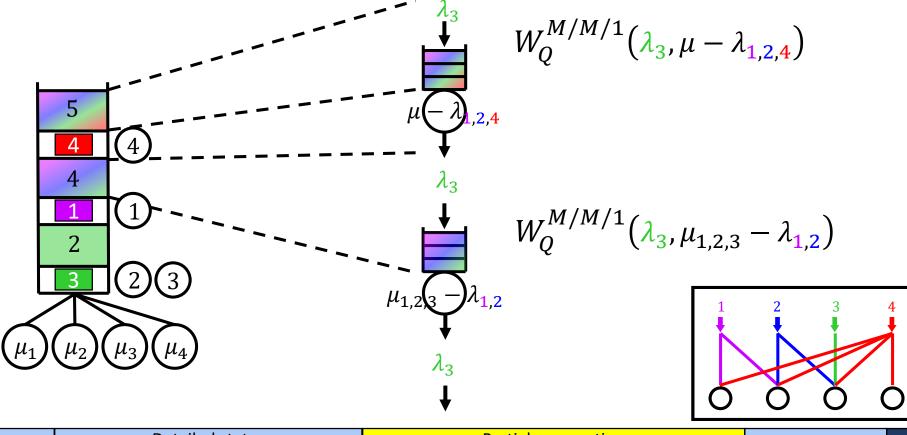


Custom	Detailed states		Partial aggregation			Polatod systems	37
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	57

$$\underline{\text{Corollary:}} N_j^{(i)} \left| \vec{d}_l =_{st} N_j^{(i)} \left| \vec{d}_j \sim \text{Geom} \left(1 - \frac{\lambda_i}{\mu\left(\vec{d}_j\right) - \lambda\left(R\left(\vec{d}_j\right)\right) + \lambda_i} \right) \right|$$

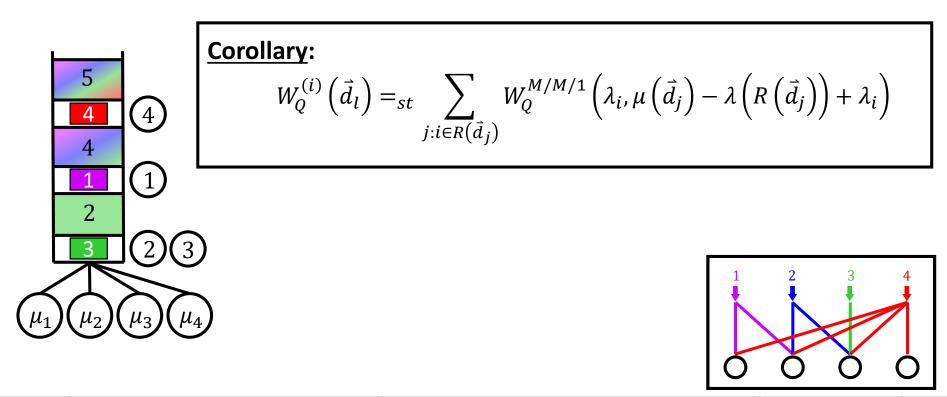


 $W_Q^{(i)}\left(\vec{d}_l\right)$ = time in queue for a class-*i* job, given it sees service profile \vec{d}_l $W_Q^{M/M/1}(\lambda,\mu)$ = time in queue in an M/M/1 with arrival rate λ and service rate μ



Suctors	Detailed states		Partial aggregation			Polatod systems	20
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	20

 $W_Q^{(i)}\left(\vec{d}_l\right)$ = time in queue for a class-*i* job, given it sees service profile \vec{d}_l $W_Q^{M/M/1}(\lambda,\mu)$ = time in queue in an M/M/1 with arrival rate λ and service rate μ



Custom	Detailed states		Partial aggregation			Polatod systems	39
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	39

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

Relating the models

• Partial aggregation

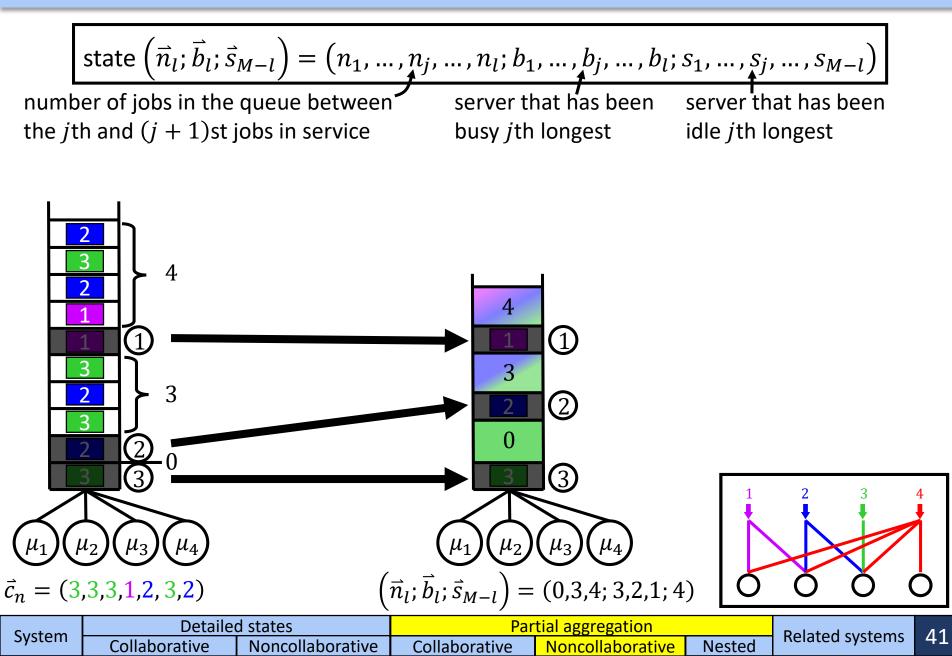
Collaborative model

Noncollaborative model

- Special case: fully flexible class
- Special case: nested systems
- Related product-form systems

Sustan	Detailed states		Partial aggregation			Polatod systems	40
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	40

Partial Aggregation: Noncollaborative ALIS



Partial Aggregation: Noncollaborative

Thm: Under ALIS,

$$\pi\left(\vec{n}_{l}; \vec{b}_{l}; \vec{s}_{M-l}\right) = \pi(0; \{b_{1}, \dots, b_{M}\}; 0) \prod_{j=1}^{l} \left(\frac{\lambda\left(R\left(\vec{b}_{j}\right)\right)}{\mu\left(\vec{b}_{j}\right)}\right)^{n_{j}} \prod_{j=1}^{l} \frac{1}{\mu\left(\vec{b}_{j}\right)} \prod_{j=1}^{M-l} \frac{1}{\lambda\left(\vec{s}_{j}\right)}$$
where \vec{b}_{l} denotes the set of busy servers ordered by the arrival times of the jobs they are serving.

<u>Thm</u>: Under random assignment (with activation rate condition), $\pi\left(\vec{n}_{l}; \vec{b}_{l}\right) = \pi(0; 0) \prod_{j=1}^{l} \left(\frac{\lambda\left(R\left(\vec{b}_{j}\right)\right)}{\mu\left(\vec{b}_{j}\right)}\right)^{n_{j}} \prod_{j=1}^{l} \frac{\lambda_{b_{j}}^{A}\left(\vec{b}_{j-1}\right)}{\mu\left(\vec{b}_{j}\right)}$ where \vec{b}_{l} denotes the set of busy servers ordered by the arrival times of the jobs they are serving and $\lambda_{b_{j}}^{A}\left(\vec{b}_{j-1}\right)$ denotes the activation rate of server b_{j} , given \vec{b}_{j-1} .

[Adan, Visschers, Weiss]

Custom	Detailed states		Partial aggregation			Polatod systems	10
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	42

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

Relating the models

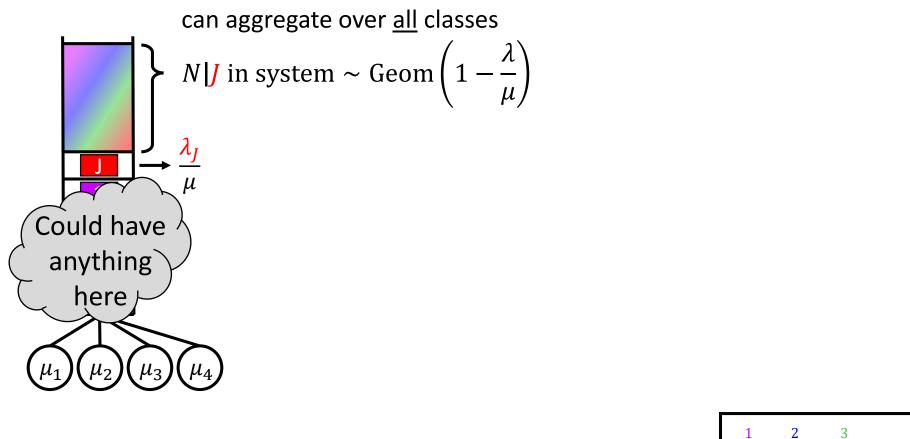
• Partial aggregation

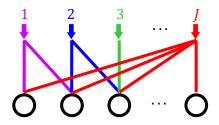
Collaborative model Noncollaborative model

- Special case: fully flexible class
- Special case: nested systems
- Related product-form systems

Sustam	Detailed states		Partial aggregation			Related systems	40
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	45

Fully Flexible Class: Collaborative Model





Custom	Detailed states		Partial aggregation			Related systems	44
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	44

Fully Flexible Class: Collaborative Model

$$N_Q^{(J)}|J \text{ in system} \sim \text{Geom}\left(1 - \frac{\lambda_J}{\mu - \lambda + \lambda_J}\right) \text{ (by the same lemma used for partial aggregation)}$$

$$N^{(J)} = \Pr\{J \text{ in system}\} \cdot \left(1 + N_Q^{(J)}|J \text{ in system}\right)$$

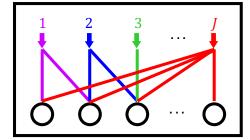
$$\sim \text{Geom}\left(1 - \frac{\lambda_J}{\mu - \lambda + \lambda_J}\right)$$

$$\text{as long as } \Pr\{J \text{ in system}\} = \rho_J = \frac{\lambda_J}{\mu - \lambda + \lambda_J}$$

$$(\text{short proof, won't show here})$$

Fully flexible class experiences M/M/1 response time:

$$W^{J} =_{st} W^{M/M/1} \left(\lambda_{J}, \mu - \lambda + \lambda_{J} \right) =_{st} W^{M/M/1} \left(\lambda, \mu \right)$$



Sustan	Detailed states		Partial aggregation			Polatod systems	лл
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	44

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

Relating the models

• Partial aggregation

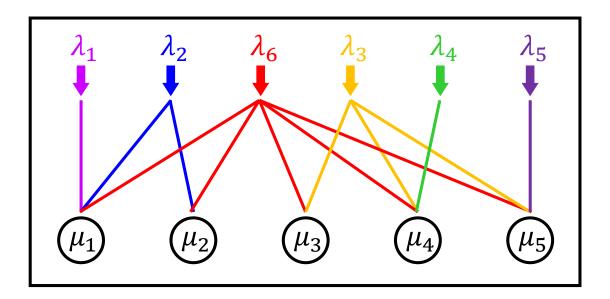
Collaborative model Noncollaborative model

- Special case: fully flexible class
- Special case: nested systems
- Related product-form systems

Sustam	Detailed states		Partial aggregation			Related systems	1 E
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	45

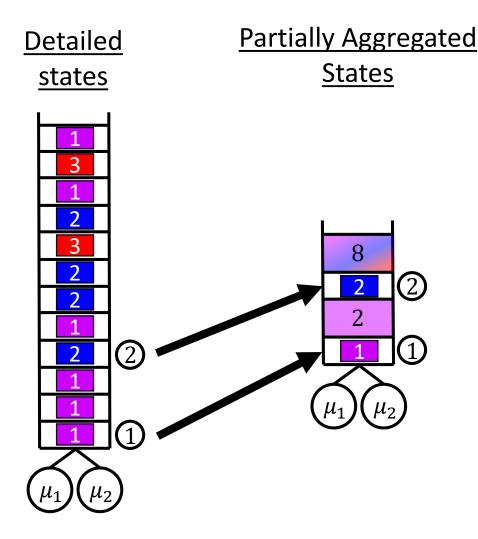
For every pair of job classes i and j, either: • $S_i \subset S_j$

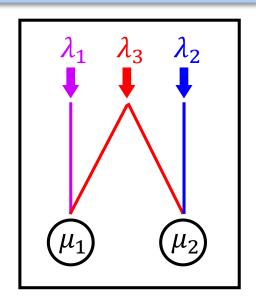
- $S_j \subset S_i$
- $S_i \cap S_j = \emptyset$



Recursive structure: removing the fully flexible class leaves two smaller nested systems

Sustam	Detailed states		Partial aggregation			Polated systems	16
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	40



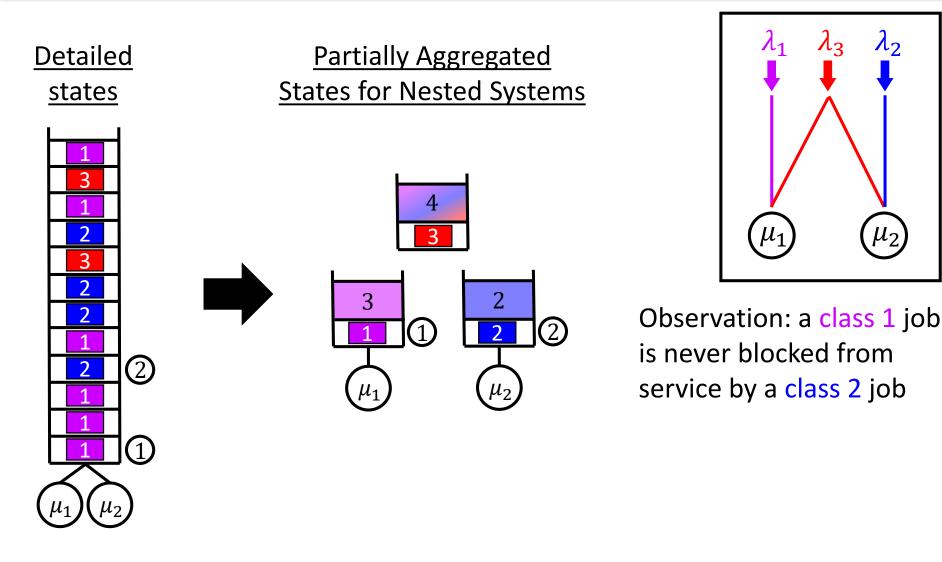


Observation: a class 1 job is never blocked from service by a class 2 job

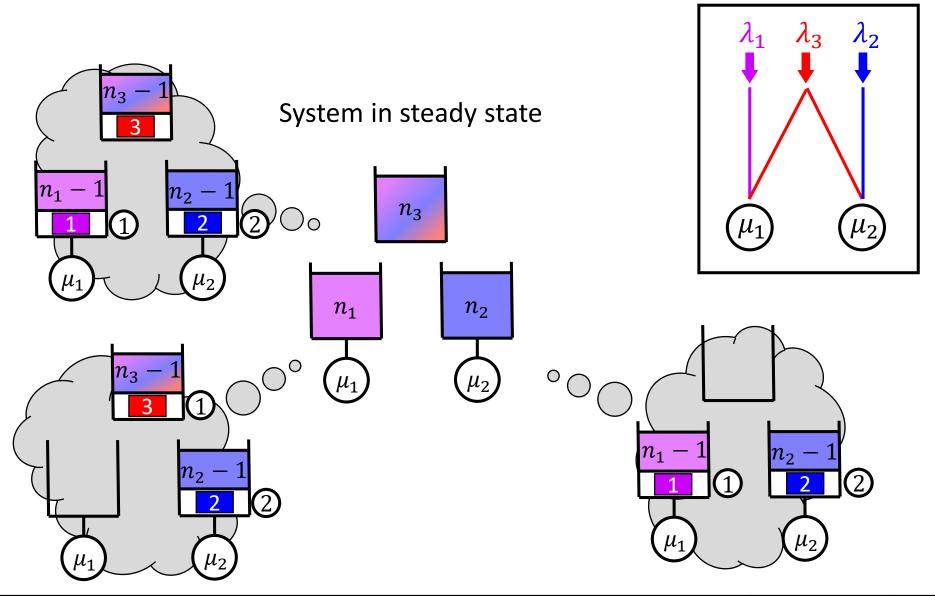
System	Detailed states		Partial aggregation			Polatod systems	17
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	47

 λ_2

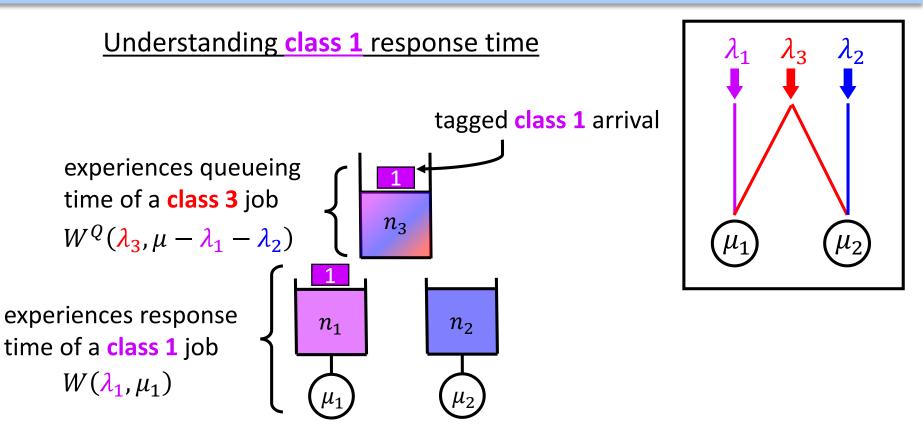
ч₂



Sustam	Detailed states		Partial aggregation			Related systems	10
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	40

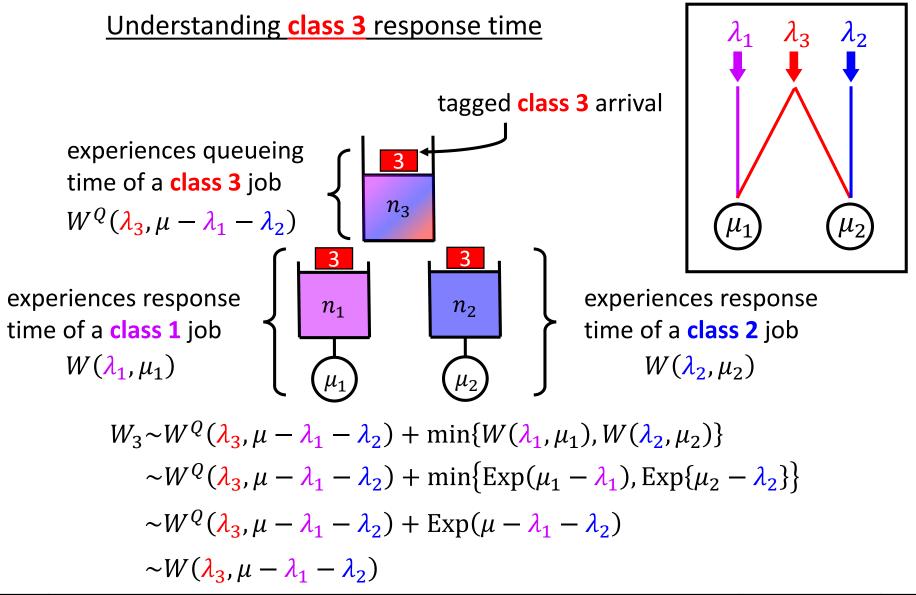


Sustan	Detailed states		Partial aggregation			Related systems	10
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	49

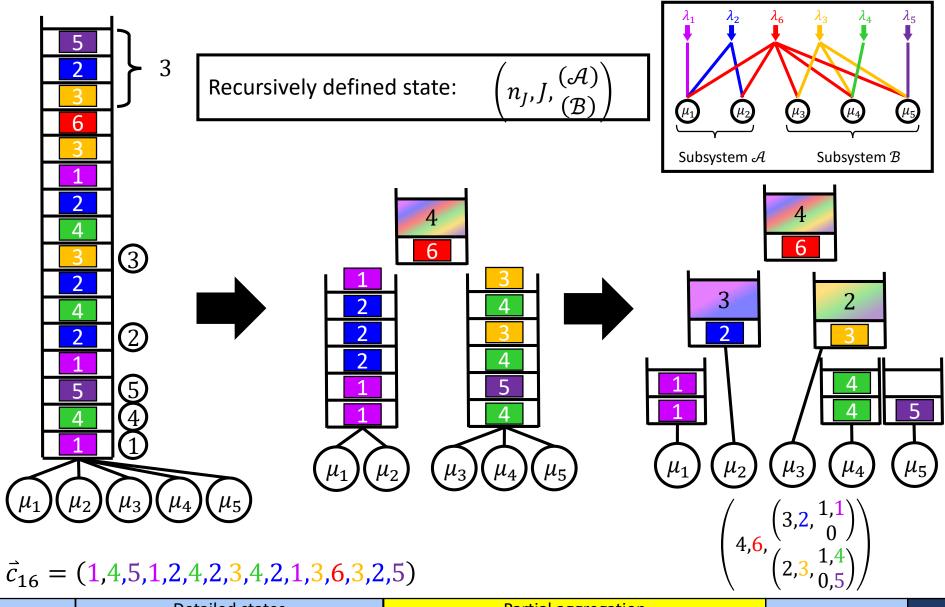


$$W_1 \sim W^Q(\lambda_3, \mu - \lambda_1 - \lambda_2) + W(\lambda_1, \mu_1)$$

Sustan	Detailed states		Partial aggregation			Polatod systems	50
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	50

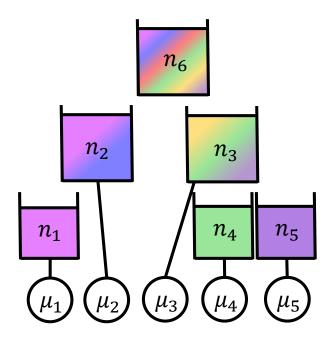


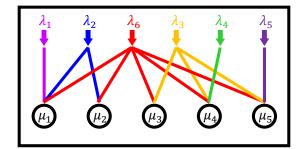
System	Detailed states		Partial aggregation			Related systems	E 1
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	ЪТ



System	Detailed states		Partial aggregation			Related systems	E 2
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	52

$$\frac{\text{Thm:}}{\pi\left(n_{J}, J, \binom{\mathcal{A}}{\mathcal{B}}\right)} = \left(1 - \rho_{J}\right) \left(\frac{\lambda\left(R(S_{J})\right)}{\mu(S_{J})}\right)^{n_{J}} \left(\frac{\lambda_{J}}{\mu(S_{J})}\right) \pi(\mathcal{A})\pi(\mathcal{B})$$
where $\rho_{i} = \frac{\lambda_{i}}{\mu(S_{i}) - \lambda(R(S_{i})) + \lambda_{i}}$
[Gardner, Harchol-Balter, Hyytiä, Righter]



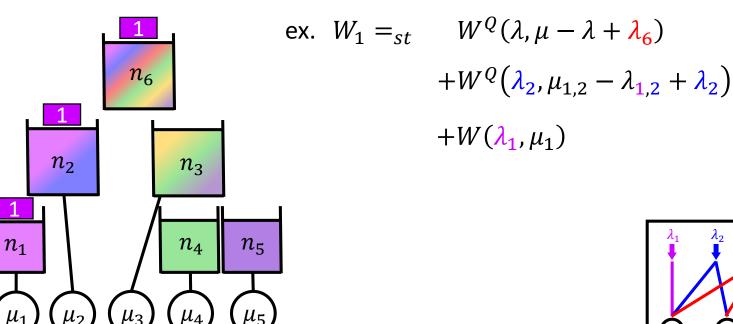


System	Detailed states		Partial aggregation			Polatod systems	E C
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	53

Deriving Performance Metrics

Corollary:

$$W_{i} =_{st} W\left(\lambda(R(S_{i})), \mu(S_{i})\right) + \sum_{j:S_{i} \subset S_{j}} W^{Q}\left(\lambda_{j}, \mu(S_{j}) - \lambda(R(S_{j})) + \lambda_{j}\right)$$



$$\lambda_1$$
 λ_2 λ_6 λ_3 λ_4 λ_5
(μ_1 (μ_2 (μ_3 (μ_4 (μ_5)

System	Detailed states		Partial aggregation			Related systems	ΓΛ
	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	54

Outline

- System description
- Review: reversibility
- Detailed states

Collaborative model

Noncollaborative model

Relating the models

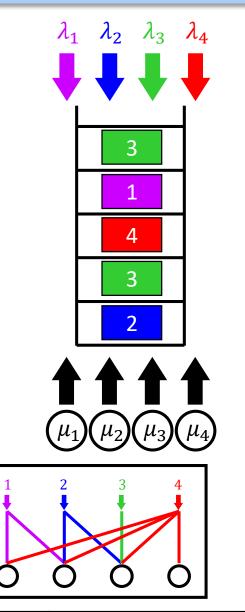
• Partial aggregation

Collaborative model Noncollaborative model

- Special case: fully flexible class
- Special case: nested systems
- Related product-form systems

System	Detailed states		Partial aggregation			Polatod systems	EE
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	55

Matching Models



Model 1: arriving jobs wait in the queue for a compatible server, arriving servers match the first compatible job and leave the system (even if unmatched)

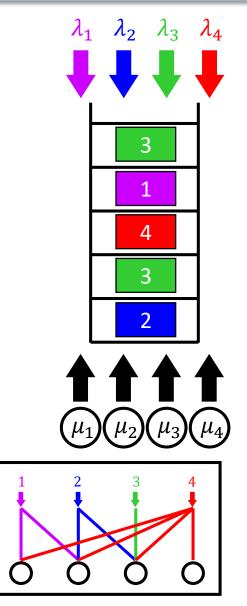
Sample path equivalences for \vec{c}_n :

Noncollaborative	Collaborative
model given busy 🔶 Mo	del 1 🛑 🛛 model
(queue state)	(system state)

[Adan, Kleiner, Righter, Weiss]

System	Detailed states		Partial aggregation			Related systems	EC
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	50

Matching Models



Other matching models with product form

Model 2 (FCFS infinite bipartite matching): arrivals are job-server pairs, both of which can queue; arriving jobs (servers) match the first compatible server (job) if any, otherwise join queue

[Adan, Busic, Gupta, Mairesse, Weiss]

<u>Thm</u>:

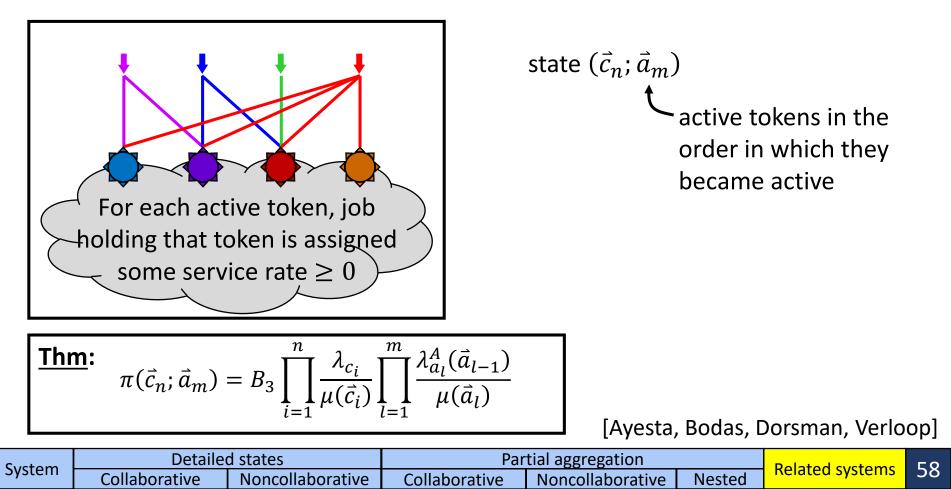
$$\pi(\vec{c}_n; \vec{s}_n) = \pi(0; 0) \prod_{i=1}^n \frac{\lambda_{c_i}}{\mu(\vec{c}_i)} \frac{\mu_{s_i}}{\lambda(\vec{s}_i)}$$

Model 3: individual arrivals, non-bipartite matching graph, arrivals match the first compatible item in queue if any, otherwise join queue [Busic, Mairesse, Moyal, Perry]

System	Detailed states		Partial aggregation			Related systems	57
	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	57

Unifying Token Model

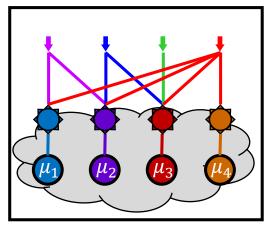
- Set of tokens, bipartite matching between jobs and tokens
- Arriving job takes compatible token if one is available (assignment condition)
- Only jobs with tokens can be served
- OI condition on tokens defines service process



Unifying Token Model

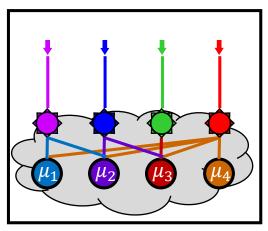
- Set of tokens, bipartite matching between jobs and tokens
- Arriving job takes compatible token if one is available (assignment condition)
- Only jobs with tokens can be served
- OI condition on tokens defines service process

Noncollaborative Model



 $\mathsf{tokens} \leftrightarrow \mathsf{servers}$

Collaborative Model



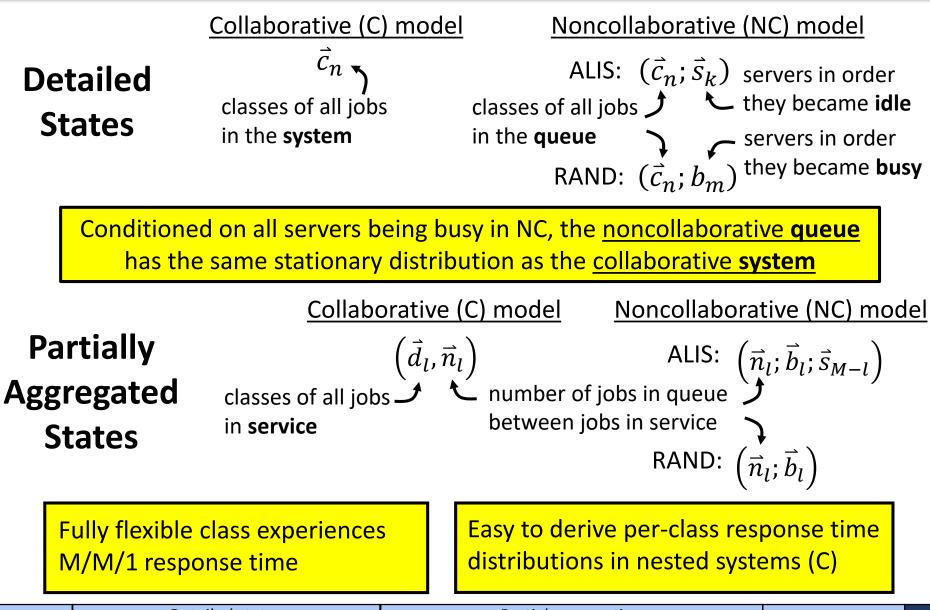
tokens \leftrightarrow job classes

...but much more general than these two models

e.g., MSCCC queue [Ayesta, Bodas, Dorsman, Verloop]

System	Detailed states		Partial aggregation			Related systems	FO
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	29

Summary and Conclusions: Part 1



System	Detailed states		Partial aggregation			Related systems	60
System	Collaborative	Noncollaborative	Collaborative	Noncollaborative	Nested	Related systems	00